# Motion control for servo or stepper motors



#### **PCI** 32-bit



Also for *CompactPCI*<sup>TM</sup> See CPCI-8004 page 136





Customer-tailored modifications designed to suit your needs. Hardware and software, firmware, PLDs, ... Contact us! The board APCI-8001 for the PCI-bus is used for the control of up to 8 servo or stepper motor axes through a PC. With this intelligent and flexible board, many control tasks from simple to complicated can be realised.

The board has three stepping/direction output channels (D/A channels, 16-bit). They are isolated from the digital current supply and are used for the control of commercially available power amplifiers connected as speed controlling devices or current regulators.

Incremental encoders, SSI encoders and EnDat encoders as well as end and reference switches can be connected to each axis channel.

Digital PID filters with forward compensation and optional Notch filters or Langham controllers are also involved in the axis control.

The "open" controlling concept of the APCI-8001 is intended in the first place for manufacturers of special-purpose machines and users which need a flexible integration as well as a CNC solution.

## Features

### Hardware/properties

- Intelligent board based on a 64-bit RISC processor
- Positioning of up to 3 axes either with servo or stepper motors. Mixed operating of servo and stepper motors possible. Up to 8 axes with slave board
- Interface for all commercially available power amplifiers
- All input and output channels are optically isolated
- A multiple-axis system can be realised by inserting several APCI-8001 in the same PC.

### Software

- Linear, circular, helical, spline and CAD interpolation
- Point-to-point movement with independent control of each axis
- Function library for Pascal, C-Basic, Borland Delphi, Borland C++, Visual Basic, Visual C++
- Programming through a PC application software or stand-alone
- The operating program can be easily adapted to specific requirements using program modules supplied with the board

# APCI-8001

For 3 servo or stepper motors

Onboard 64-bit RISC processor

**Optical isolation** 

16-bit analog output channels

Can be extended to a total of 8 axes

Menu-driven test application

- User programs created with the compiler can be processed automatically
- Multitasking: the board can simultaneously process up to 4 user programs.

### **Applications**

- CNC control
- Semi-conductor manufacturing
- Event counting
- Axis control
- Axis positioning
- Robots
- Stepper motor controlMachine monitoring
- Nachine monitoring
- Research and development

# Software

#### Drivers:

Windows XP/2000/NT 4.0: API as 32-bit DLL + SYS drivers. Delphi 2.0 interface, Microsoft C Lib., Borland C Lib.

Windows 9x/Windows ME: API als 32-bit DLL + VXD-Drivers. Delphi 2.0 interface, Microsoft C Lib., Borland C Lib. Windows Vista (32-bit) Linux kernel version 2.4/2.6 Supplied with the board: Stand-alone program

### Samples:

Example for Visual Basic 4.0 (32-bit version), Visual C++, Borland Delphi



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APCI-8001	
CPU system:	64-bit-RISC processor 150 MHz
RAM:	16 MB
Data exchange with the PC:	Through PCI bus
Controller software:	PIDF (PID filters with forward compensation)
Interpolation:	2D 3D linear, 2D circular, 3D circular, 3D helix,
	spline, asynchronous and synchronous interpolation
	with secondary axes.
	With OPMF-8001 all interpolations
	2D8D depending on the number of axes
Inputs for incremental encoders:	Diff. or TTL max. 2 MHz
	Word length: 32-bit with sign
	Optional max. 10 MHz (40 MHz after quadrupling)
Inputs for SSI encoders:	Up to 32-bit, gray / binary code,
	variable frequency 30 KHz to 2 MHz
Setpoint value outputs (Servo):	1 per channel, D/A converter,
	16-bit resolution, $\pm$ 10 V
Pulse outputs (stepper motors):	1 stepper signal (RS422) and 1 directional signal
	(RS422) for each channel, pulse frequency up to 2 MHz
Isolated digital inputs:	16 inputs, 24 V, as end, reference switch
	or freely programmable
Isolated digital outputs:	8 channels, 24 V / 500 mA, for releasing
	the power amplifiers or freely programmable
Interrupts:	Through PCI BIOS
DMA:	Bus master
Auxiliary voltage:	24 V external for digital I/O
Safety	

# Optical isolation:

1000 V

### EMC – Electromagnetic compatibility

The product complies with the European EMC directive. The tests were carried out by a certified EMC laboratory in accordance with the norm from the EN 61326 series (IEC 61326). The limit values as set out by the European EMC directive for an industrial environment are complied with. The respective EMC test report is available on request.

# Physical and environmental conditions

Dimensions:	175 x 106 mm		
System bus:	PCI 32-bit 3.3/5 V acc. to spec. 2.2 (PCISiG)		
Space required:	Board APCI-8001: 1 PCI slot		
	Slave board OPMF: 1 PCI slot		
	Cable FB8001: 1 slot opening		
Operating voltage:	+ 5 V and 3.3 V $\pm$ 5 % from the PC		
Front connector APCI-8001:	Axis 1, 2, 3: 50-pin SUB-D male connector		
Front connector OPMF-3001:	Axis 4, 5, 6: 50-pin SUB-D male connector		
Ribbon cable FB8001:	Axis 7, 8: 50-pin SUB-D male connector		
Temperature range:	0 to 60 °C (with forced cooling)		



# Pin assignment - 50-pin SUB-D male connector

		-		Pin
41         Setepoint value 3 / step 3           55         Setepoint value 3 / step 3           50         True value 3           37         True value 3           38         True value 3           39         True value 3           30         True value 3           30         True value 3 / step 3           40         True value 3 / step 3           41         True value 3 / step 3           42         Dig. input 9           42         Dig. input 10           43         Dig. input 12           45         Dig. input 12           46         Dig. input 14           48         Dig. input 14           49         Dig. input 16           40         Dig. input 16           40         Dig. input 16	<ul> <li>8 Setpoint value 2/step 2</li> <li>9 Setpoint value 2/step 2</li> <li>20 True value 2</li> <li>21 True value 2</li> <li>22 True value 2</li> <li>23 True value 2</li> <li>24 True value 2</li> <li>25 True value 2</li> <li>26 Dig. output 1</li> <li>27 Dig. output 3</li> <li>29 Dig. output 4</li> <li>30 Dig. output 5</li> <li>31 Dig. output 7</li> <li>33 Dig. output 8</li> </ul>	34 35 36 37 38 39 40 41 42 42 44 44 45 46 45 49 50 33	Setpoint value 16/sep 1           2 Setpoint value 16/sep 1           3 True value 1           4 True value 1           5 True value 1           6 True value 1           7 True value 1           7 True value 1           7 True value 1           9 Dig. input 1           10 Dig. input 2           11 Dig. input 2           12 Dig. input 4           13 Dig. input 4           14 Dig. input 5           15 Dig. input 6           15 Dig. input 7           17 + 24 V	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17

# **ADDI-DATA** connection

Example for an 8-axes system PX 8000 APCI-8001: Standard 1 up to 3 axes SUB-D OPMF/8A: 5 axes, including 3 on the 50-pin front connector and 2 on the connector for ribbon cable FB8001 50-pc PX 8000 50-pol. Slave board OPMF 0-pol APCI-8001 SUB-D-female connecto SUB-D male connecto

FB-INTERBUS: Ribbon cable between OPMF and 9-pin SUB-D male

# **Ordering information**

PX 8000

### APCI-8001

APCI-8001: Motion control board for servo or stepper motors. 16 dig. inputs and 8 dig. outputs, 24 V, optically isolated. Incl. technical description, software drivers. APCI-8001-STP: Motion control board for stepper motors. 16 dig. inputs and 8 dig. outputs, 24 V, optically isolated. Incl. technical description and software drivers.

## Options:

Fax:

OPMF/4A (OPMF/4-STP)	: 4th axis – 8 inputs and 4 dig. outputs in addition		connector with bracket for connecting the INTERBUS.
OPMF/5A (OPMF/5-STP)	5th axis – 16 inputs and 8 dig. outputs in addition	OPT.CAN-8001:	CAN bus connection of the APCI-8001 (not CAN Open).
OPMF/6A (OPMF/6-STP	6th axis – 16 inputs and 8 dig. outputs in addition	Accessories:	
For the option OPMI	-/7 and more the FB8001 cable is required	FB-CAN:	Ribbon cable between OPMF and 9-pin SUB-D male con-
OPMF/7A (OPMF/7-STP)	7th axis – 24 inputs and 12 dig. outputs in addition		nector with bracket for connecting the CAN bus.
OPMF/8A (OPMF/8-STP)	8th axis – 24 inputs and 12 dig. outputs in addition	FB8001:	From the 7th axis on (OPMF/7, OPMF/8) or with option
OPMF-AI12:	4 analog inputs (option available in single or double,		OPMF-AI12. Ribbon cable between OPMF and a
	max. 8 analog inputs).		50-pin SUB-D male connector with bracket.
OPMF-DIO:	8 digital inputs and 4 dig. outputs, optically isolated		On request with female connector.
	(option available up to 3 times, max. 24 dig. inputs	FBRELAY:	For releasing the relays
	and 12 outputs)		FBRELAY-9: Standard, 9-pin cable with bracket
OPMF-AO:	1 analog output, option available up to 5 times		FBRELAY-25: more than 3 axes: 25-pin cable.
	(max. 8 analog outputs)	PX 8000:	Screw terminal panel with housing for DIN rail
	(output is only free when the axis is not used)	ST8001:	Cable for connecting APCI-8001 and OPMF, 50-pin.
OPT.INTERBUS-8001:	Master connection of the APCI-8001		

