## Motion control board for 4 servo or stepper motors







The board CPCI-8004 was developed in order to come up with the growing requirements in motion control and positioning. With this intelligent and flexible board, many control tasks from simple to complicated can be realised.

The CPCI-8004 for the CompactPCI bus is used for the control of up to 8 servo or stepper motor axes on the basis of a CompactPCI computer system.

The board has four stepper/direction output channels (16-bit D/A channels). They are isolated from the digital current supply and are used for the control of commercially available power amplifiers connected as speed controlling devices or current regulators. Each channel is assigned an input channel used for the connection of all common incremental or SSI encoders for reference switch.

Digital PID filters with forward compensation and optional Notch filters or Langham controllers are also involved in the axis control.

The "open" controlling concept of the CPCI-8004 is intended in the first place for manufacturers of special-purpose machines and users which need a flexible integretation as well as a CNC solution.

#### **Features**

#### Hardware features

- Intelligent board based on a 64-bit RISC processor
- Positioning of up to 4 axes either with servo or with stepper motors. Mixed operating of servo and stepper motors possible.
- Positioning of up to 8 axes with slave board • Interface for all commercially available power
- amplifiers
- All input and output channels are isolated
- A multiple axis system can be realised by inserting several CPCI-8004 in the same system.

#### Software

- Linear, circular, helical, spline and CAD interpolation
- Point-to-point movement with independent control of each axis
- Function library for Pascal, C-Basic, Borland Delphi, Borland C++, Visual Basic, Visual C++
- Programming through a PC application software or stand-alone
- The operating program can be easily adapted to specific requirements using program modules supplied with the board
- User programs created with the compiler can be processed automatically

## **CPCI-8004**

For 1 up to 8 servo or stepper motors

**On-board 64-bit RISC processor** 

#### **Optical isolation**

16-bit analog output channels

40 dig. inputs and 24 dig. outputs, isolated

#### **Open system**

Menu-driven test application

• Multitasking: the board can simultaneously process up to 4 user programs.

#### Noise immunity

- Test level:
- ESD: 4 kV
- Fields: 10 V/m
- Burst: 4 kV
- Conducted radio interferences: 10 V

#### EMC tested according to 89/336/EEC

In preparation

#### Applications

- Precision positioning
- CNC control
- Semi-conductor manufacturing
- Event counting
- Axis control
- Robots
- X-Y-Z positioning control
- Stepper motor control
- Machine monitoring
- Research and development

#### Software drivers

A CD-ROM with the following software and programming examples is supplied with the board.

#### **Drivers:**

Windows NT 4.0 and Windows XP/2000: API als 32-Bit DLL + SYS- driver. Delphi 2.0 interface, Microsoft C Lib., Borland C Lib. Windows 9x/Windows ME: API as 32-Bit DLL + VXD driver. Delphi 2.0 interface, Microsoft C Lib., Borland C Lib. Linux: on request Also delivered: stand alone program

#### Samples:

Samples for Visual Basic 4.0 (32-bit version), Visual C++, Borland Delphi

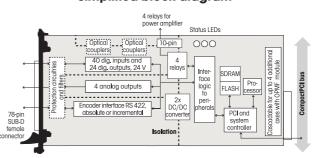
# Motion control board for 4 servo or stepper motors



## **CPCI-8004**

#### **Specifications** CPU system: 64-bit RISC processor 150 MHz RAM: 32 MB Data exchange with the PC: through Dual Port Memory approx. 100 kB Controller software: PIDF (PID filter with forward compensation) 2D .. 8D linear, 2D zircular, 8D circular, 8D helical, Interpolation: spline, asynchronous and synchronous interpolation with secondary axes. Inputs for incremental encoders: Diff. or TTL max. 2.1875 MHz (8.75 MHz after quadrupling). Word length: 32-bit with sign up to 32-bit, gray/binary code variable Inputs for SSI encoders: frequency 30 KHz, 2.1875 MHz Setpoint value outputs (servo): 1 for each channel, D/A converter, 16-bit resolution, ± 10 V 1 stepper signal (RS422) and 1 directional signal Pulse outputs (stepper): (RS422) for each channel, pulse frequency up to 10 MHz Isolated digital inputs: 40 inputs, 24 V, as end or reference switch or freely programmable 24 channels, 24 V/500 mA, for releasing the Isolated digital outputs: power amplifier or freely programmable Through PCI BIOS Interrupts: DMA: Bus master Auxiliary voltage: 24 V external for dig. I/O Interbus/CAN-Bus Options Safety 1000 V Optical isolation: Noise immunity - ESD: 4 kV - Fields: 10 V/m Test level: - Burst: 4 kV - Cond. radio interferences: 10 V **Physical and environmental conditions** Dimensions: 3U/4TE System bus: CompactPCI 32-bit 5 V acc. to spec. 2.1 (PCISIG) Board CPCI-8004: 1 slot Place required: Slave board OPMF-C: 1 slot Cable FB8001-C: 1 slot opening Operating voltage: + 5 V, ± 5 % from the PC Front connector CPCI-8004: Axis 1, 2, 3, 4: 78-pin SUB-D female connector

## Simplified block diagram



### **ADDI-DATA** connection

#### Example for ein 8-axes-System

CPCI-8004: Standard 1 to 4 axes OPMF/8C: 8 axes, incl. 4 on the 78-pin front connector Cable FB8001-C: for option OPMF-AI12, 4 analog inputs Options: Interbus / CAN Bus



**ORDERING INFORMATION** 

## ADDIPOS CPCI-8004

Front connector OPMF-C:

Temperature ranae

CPCI-8004: Axis control board for 4 servo or stepper motor axes. Incl. technical description and software drivers

Axis 5, 6, 7, 8: 78-pin SUB-D female connector

0 to 60°C (with forced cooling)

Zubehör			
OPMF-C:	Slave board for an extension of up to 8 axes	OPMF/AI12-C:	4 analog inputs, 12-bit resolution
OPMF/5C:	Extension to 5 axes in total		each channel can be set to the following
OPMF/6C:	Extension to 6 axes in total		measuring range through software:
OPMF/7C:	Extension to 7 axes in total		05 V, 010 V, -5 V+5 V, -10 V+10V
OPMF/8C:	Extension to 8 axes in total		This module is available as single or double
		FB8001-C:	Ribon cable between OPMF/AI12C and a 20-pin
			SUB-D male connector with bracket

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